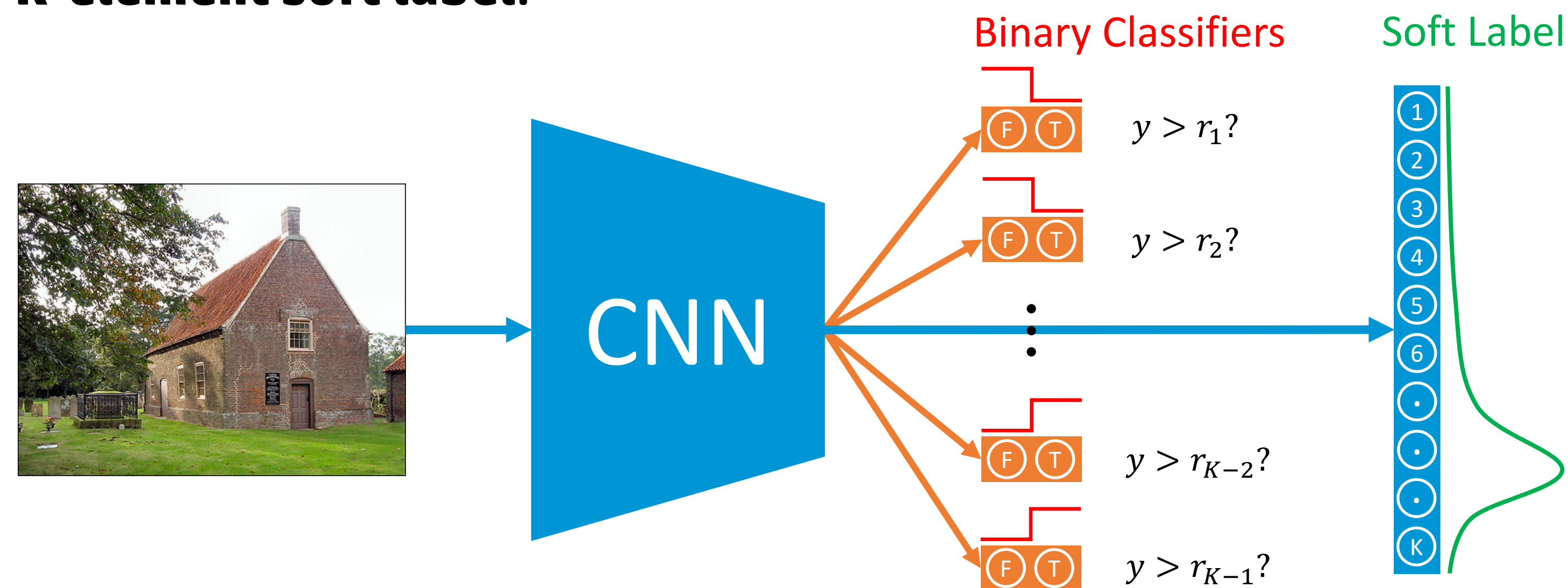


1. Objective

Our goal is to substitute the **1-hot label** representations in ordinal regression problems. Instead of building an ensemble of **K-1 binary classifiers** that distinguish rank thresholds, we use the same default, fully-connected output layer of an off-the-shelf classification CNN with a **K-element soft label**:



2. Method

Our **Soft Ordinal** labels (**SORD**) encode metric penalties *à la Softmax*:

$$y_i = \frac{e^{-\phi(r_t, r_i)}}{\sum_{k=1}^K e^{-\phi(r_t, r_k)}} \quad \forall r_i \in \mathcal{Y}$$

- $\mathcal{Y} = \{r_1, r_2, \dots, r_K\}$ is the list of ordinal ranks in the problem.
- ϕ penalizes how far a given rank is from the true value r_t .

When using Softmax and a cross-entropy loss, the computation of the gradient with respect to the output probits p_i is simply:

$$\frac{\partial L}{\partial p_i} = -\frac{e^{-\phi(r_t, r_i)}}{e^{o_i + \log C}}$$

SORD trains the network to learn features so that the outputs o_i for each rank match the interclass distance ϕ , reaching the minima when:

$$o_i + \log C = -\phi(r_t, r_i) \quad \forall r_i \in \mathcal{Y}$$

SORD Features:

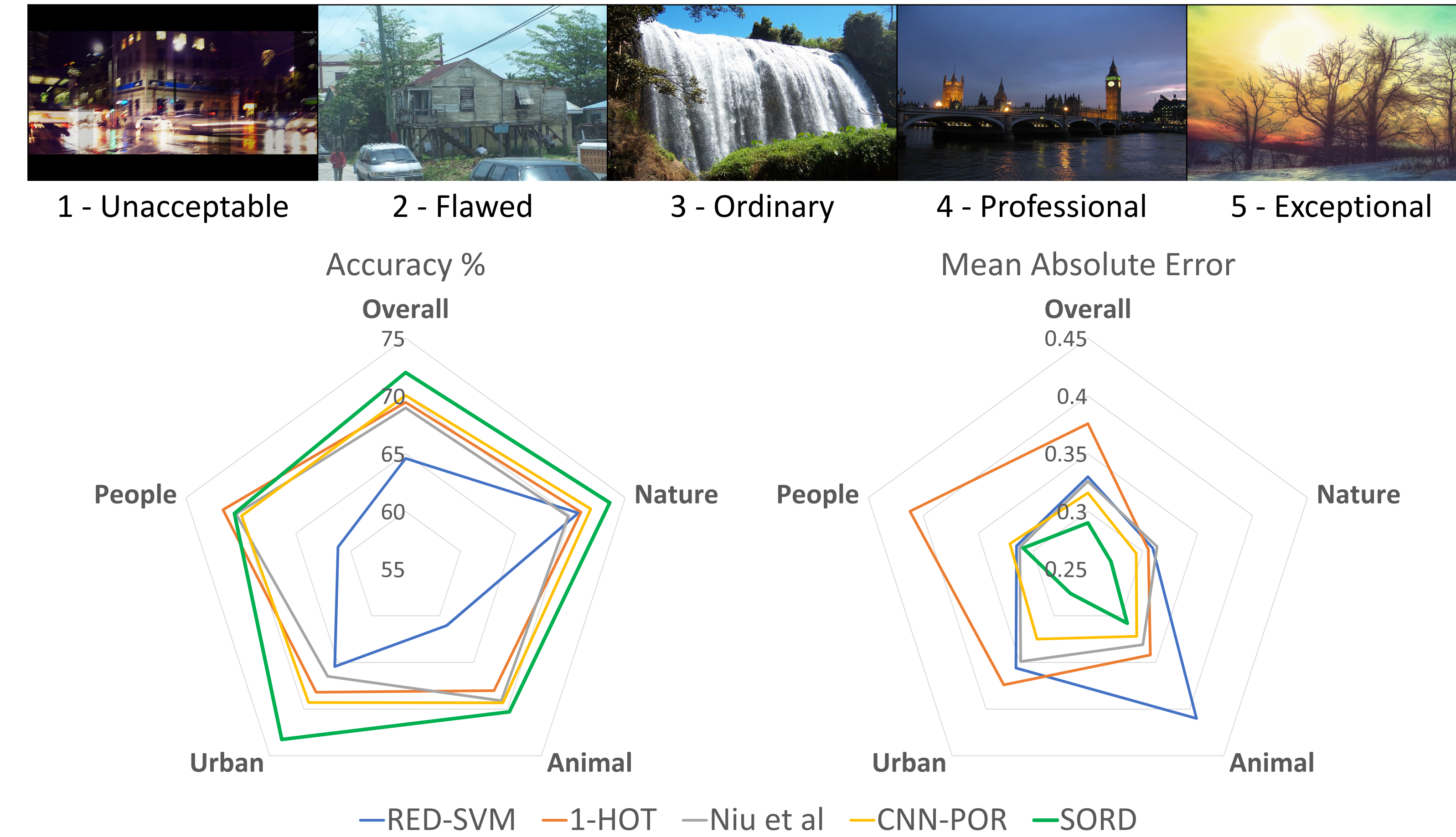
- General-purpose: a wild variety of tasks can use SORD.
- Simple to implement: just two lines of code.
- No new CNN architectures: an off-the-shelf network is sufficient.
- Inference can be done with either argmax or expected value.
- Continuous domains: ϕ is valid when $r_t \notin \mathcal{Y}$. This smoothly balances the SORD label without needing discretization or quantization.

3. Image Ranking: inputs with equally spaced labels

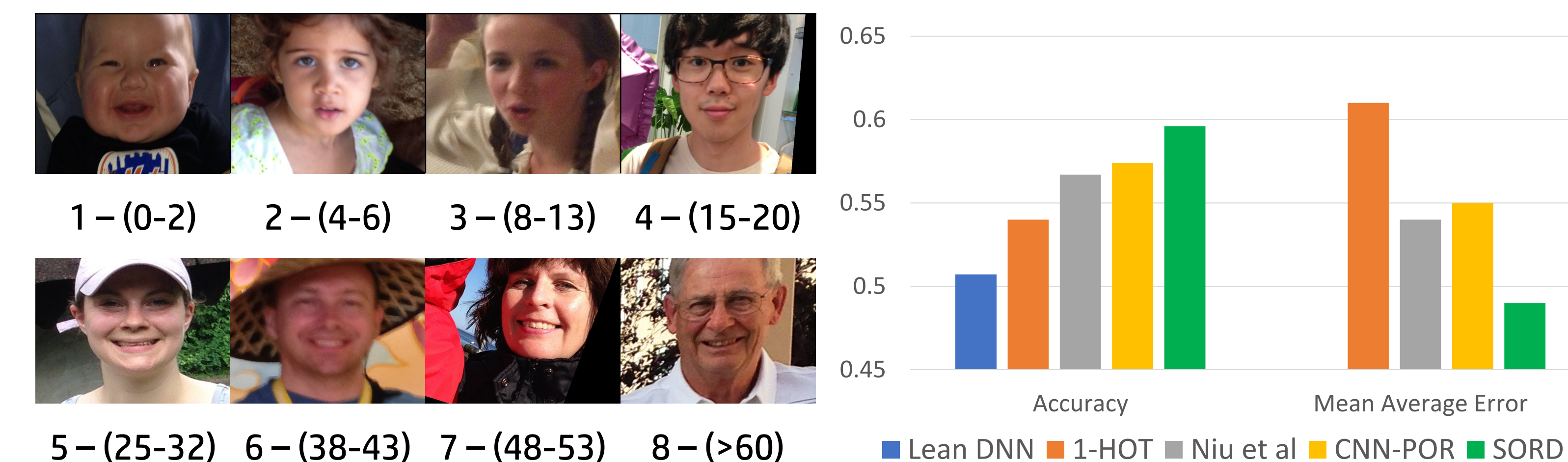
We use an off-the-shelf **VGG-16** and the metric:

$$\phi(r_t, r_i) = |r_t - r_i|$$

Image Aesthetics dataset: 15K images labeled in 5 ordinal categories



Adience dataset: 26K images labeled in 8 age groups

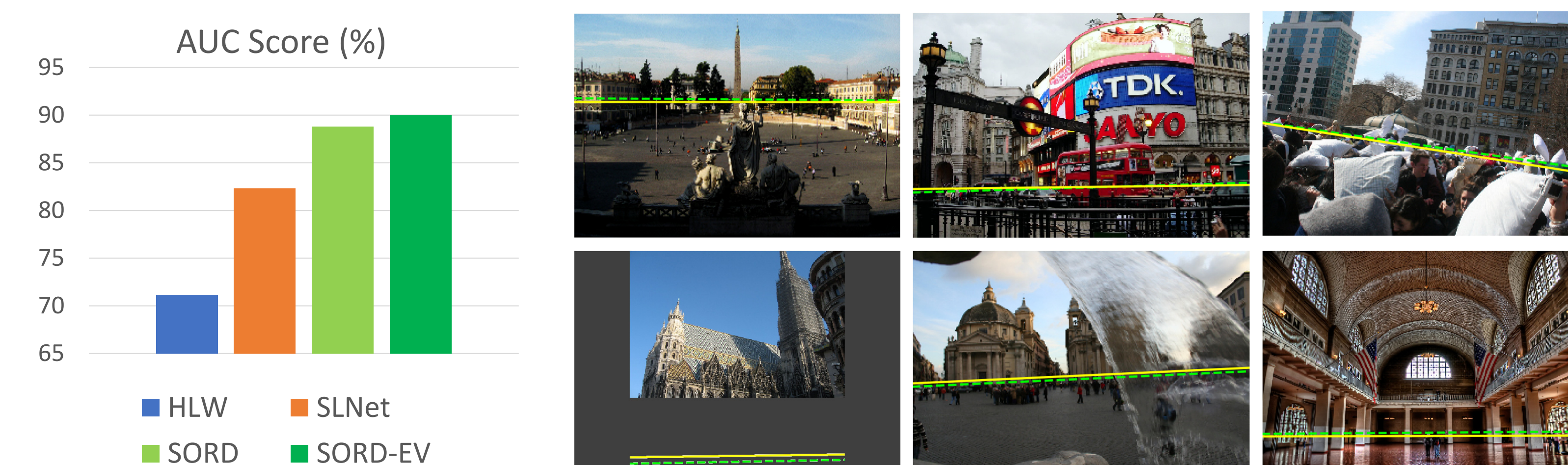


4. Horizon Lines in the Wild: 100K images from SfM models

We learn the two continuous domain line parameters by interpolating 100 bins from the training data, using **Resnet50** and the metrics:

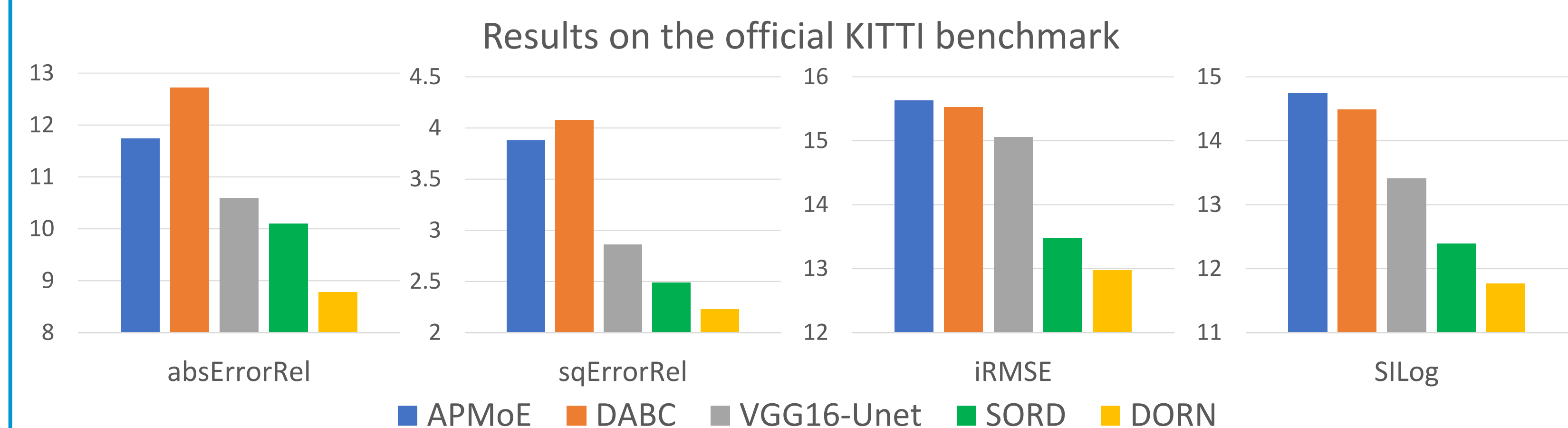
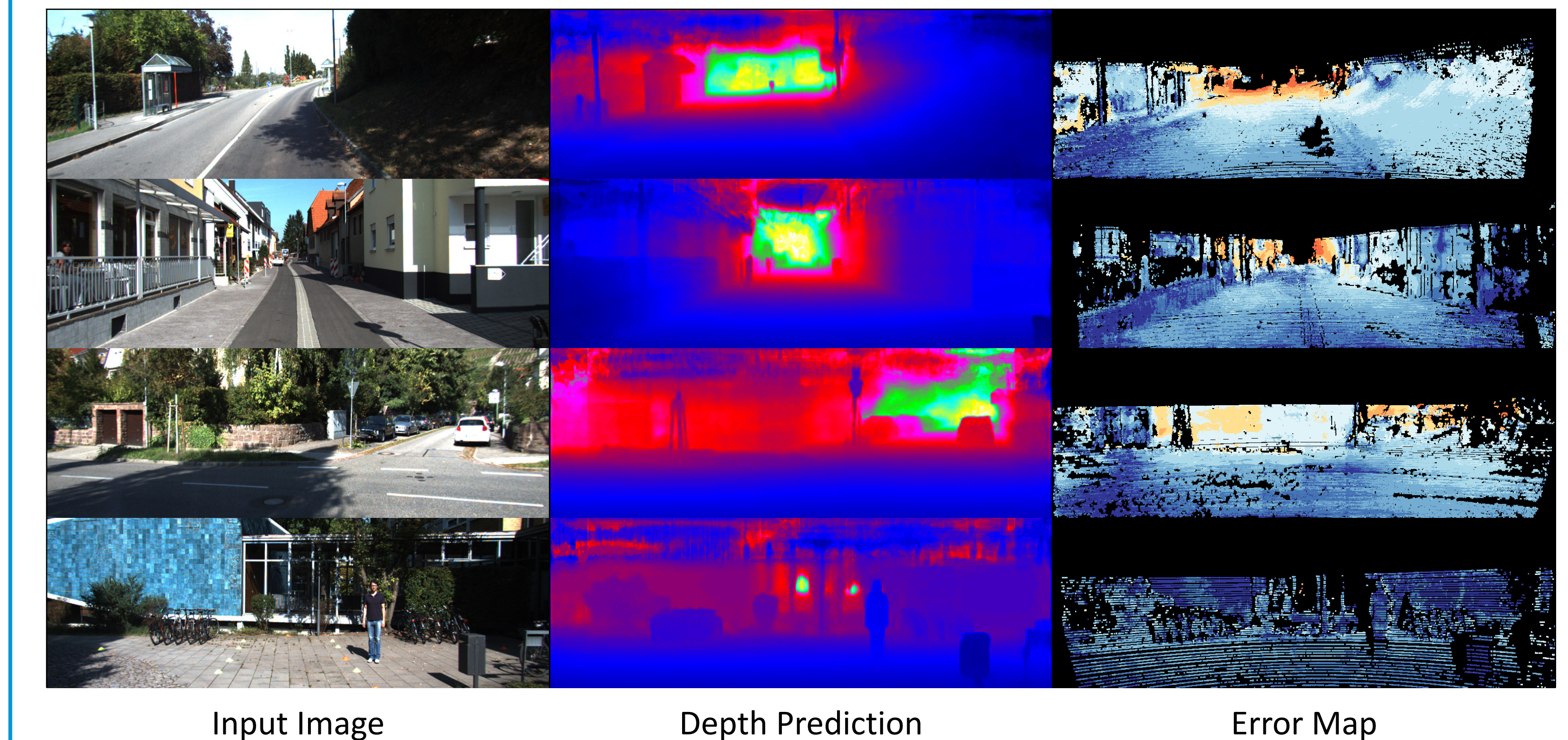
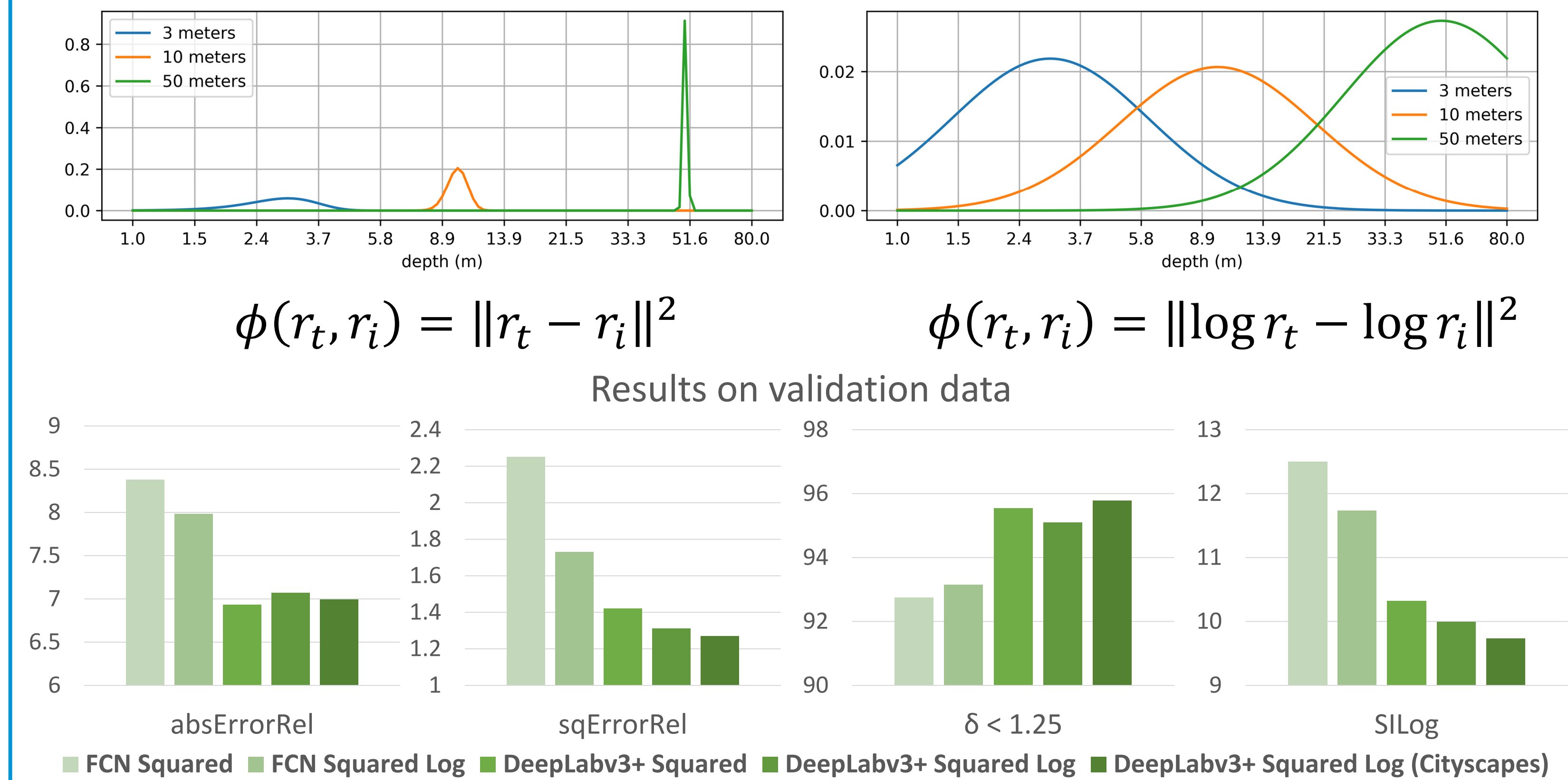
$$\phi_\theta(\theta_t, \theta_i) = \min(\|\theta_t - \theta_i\|^2, \|(\theta_t - \theta_i - \pi) \bmod 2\pi\|^2)$$

$$\phi_\rho(\rho_t, \rho_i) = \|\rho_t - \rho_i\|^2$$



5. Monocular Depth Estimation on KITTI

SORD can estimate depth using segmentation networks, adapting a scale-increasing discretization method (SID) with $K=120$ intervals:



Selected References

- [1] H. Fu, M. Gong, C. Wang, K. Batmanghelich, and D. Tao. Deep ordinal regression network for monocular depth estimation. In CVPR, 2018.
- [2] J.-T. Lee, H.-U. Kim, C. Lee, and C.-S. Kim. Semantic line detection and its applications. In ICCV, 2017.
- [3] Y. Liu, A. Wai Kin Kong, and C. Keong Goh. A constrained deep neural network for ordinal regression. In CVPR, 2018.
- [4] S. Workman, M. Zhai, and N. Jacobs. Horizon lines in the wild. In BMVC, 2016.

